



**Project** Worldskills 2024

Date 17.03.2023

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Customer No. 195586

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## Festo Didactic – Technical Education Solutions

**Festo Didactic** is the world-leading provider of equipment and solutions for industrial education. We design and implement learning centers and laboratories, educational equipment and programs that train people to perform in highly dynamic and complex industrial environments. Our goal is to maximize learning success in educational institutions and industrial companies around the globe.

Festo Didactic educational solutions directly evolve from technologies and innovations in automation and engineering. They place students in real-life situations and enable them to gain practical experience with high-tech industrial components and current systems. The product design focuses on excellence in usability and practice orientation: All functional components stand out from their complex industrial surroundings. They are easy to use and easy to remember. Their specific functions, positions and connections within the learning system intuitively show how technologies really work.

All learning environments, such as learning factories, laboratory equipment and e-learning products, are offered in conjunction with technical, organizational and people-oriented training programs – in 40 languages worldwide – and are associated with services like planning and operating complex learning centers, and with consultancy services for industrial companies.



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| Position    | Quantity     | Description                              |    |            |            |        |
| Descrip     | otion CP La  | b  |    |            |            |        |
| CP Lab –    | Industry 4.0 | right from the start                     |    |            |            |        |
| 1           |              |  |    |            |            |        |
| - 838       |              |  |    |            |            |        |
| E I         |              |  |    |            |            |        |
| 4           |              |  |    |            | Ō          | FES    |

## CP Lab – The compact Industry 4.0 learning system

The Cyber-Physical Lab is the professional and compact industry 4.0 learning system from Festo Didactic. It contains the relevant technologies and components to provide comprehensive industry 4.0 knowledge.

The modular and flexible design allows working in different learning scenarios: from the individual pallet transfer system with integrated control to the networked production facility with cloud services.



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### CP Lab – A versatile system

The modularity of the factory layout is one of the most important features of Industry 4.0. The CP Lab modules can be combined and expanded in a variety of ways.

### In sequence

By simple combinations of the individual modules, different system configurations can be realised.

#### In circulation system

The individual modules can be easily combined "over corner". This means that complete circulation systems can already be implemented with four, six, eight or ten modules.

#### In combination with mobile robot

The CP Bridge (Branch) is used, as a supplementary module for CP Lab transfer system, to transport workpiece carriers to the next working position. The CP Bridge is the main interface which enables the handover of workpieces from CP Lab to the mobile robot system Robotino® and to CP Factory modules.

The system at a glance

#### Main components:

- Integrated control
- Mono-belt transfer system
- Pallet stopper
- 3/2-way valve
- Inductive sensors
- Capacitive sensors at the beginning and end of the conveyor
- RFID-read/write sensor
- Identification system, binary
- DC or AC motor
- Motor controller, bidirectional with 2 speed levels











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| ٠          | Incremental               | encoder   |              |            |           |
| ٠          | IO-Link Mas               | ter   |              |            |           |
| •          | IO-Link Devi              |   |              |            |           |
| ٠          |                           | O via IO-Link   |              |            |           |
| •          | Control pan               | el  |              |            |           |
|            | a case control            |   |              |            |           |
|            | ocess control             |   |              | T          |           |
| In CP La   | b the workpie             | ce takes over the process control. Every carrier is equipped<br>nich workpiece parameters are stored. | Sector-      |            | 140       |
| WILLIAK    | rid-lag oli wi            | iich workpiece parameters ale stored.   | The          | II         |           |
|            |                           |   |              |            | 0         |
|            |                           |   | Ro           | Onter      | 256       |
|            |                           |   | 0            |            | STATE A   |
|            |                           |   |              |            | ny.       |
|            |                           |   |              |            |           |
| Followi    | ng applicatio             | n modules are available:  |              | 1          |           |
|            |                           |   |              |            |           |
|            |                           |   |              | <u>י</u>   |           |
| •          | Magazine                  |   |              | 1          |           |
| •          | Turning                   |   |              |            | ·         |
| ٠          | Camera insp               |   | *            | THE REAL   |           |
| ٠          | Tunnel over               | 1   | Ser la       | 0          | A POPULAT |
| •          | Drilling                  |   |              |            |           |
| •          | Press                     | alagua  | J'an I       |            |           |
| •          | Measure an<br>Workpiece o |   | er l         |            |           |
|            | Labelling                 | Julput  |              |            |           |
|            | Pick-by-Ligh              | ht  |              |            |           |
| •          | Dosing                    | 1   |              |            |           |
|            | 200                       |   |              |            |           |
| <b>F</b>   |                           |   |              |            |           |
| Further    | аррисацой п               | odules on request.  |              |            |           |
|            |                           |   |              |            |           |
|            |                           |   |              |            |           |
|            |                           |   |              |            |           |
|            |                           |   |              |            |           |
|            |                           |   |              |            |           |
|            |                           |   |              |            |           |
|            |                           |   |              |            |           |
|            |                           |   |              |            |           |



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| Position Quantity | Description                              |              |            |        |
| .ayout & Process  |  |              |            |        |

- 1) Process start: Outsourcing the front cover from the magazine
- 2) At the measuring station, two laser distance sensors are mounted above the workpiece on an adjustable measuring stand and can be partially directed to 2 measuring points. With the iDrilling module, 2 pairs of holes (simulated) can be inserted into a workpiece.
- 3)
- 4) End of the process: The output module is equipped with a biaxial handling system and is used to eject the workpieces on two roller conveyors



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| Position     | Quantity           | Description |  |  |                       |   |        |
| .ayout &     | Applications       |             |  |  |                       |   |        |
|              | tine application m |             | Analog measuring application           | Drilling application module                    |                       | but application mod   |        |
| - RFID       | ess start          | UULE        | module<br>– QS<br>– SPC<br>– Analytics | – CPS<br>– Production parameters<br>– Variants | – Pa<br>– Fle<br>– Lo | rameter processing<br>wible handling<br>gistics<br>pocess end | 5      |



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| osition      | Quantity   | Description   |                              | La contra c | •          |           |
|              |            |   |                              |  |            |           |
| CP Lab       | Pallet Tra | nsfer System stations   |                              |  |            |           |
| Pos. 1       | 4,00       | CP LAB CONVEYOR DC-1512SP   |                              |  |            | 500 m M   |
|              |            | D12501  |                              |  | -          | -         |
|              |            |   |                              |  |            |           |
|              |            |   |                              |  | 0          |           |
|              |            | Function  |                              |  | Pictur     | e similar |
|              |            | The conveyor is the main component of   |                              |  |            |           |
|              |            | workpiece carriers to the next working  |                              |  |            |           |
|              |            | workpieces is done via capacitive sension conveyor. Every carrier is equipped wi  |                              |  |            |           |
|              |            | parameters are stored. A RFID read- and   |                              |  |            |           |
|              |            | workpiece that communicates through   |                              |  |            |           |
|              |            | main Controller. The CP Lab Conveyor  |                              |  |            |           |
|              |            | interfaces in order to be complemente<br>communicate with the MES.                | יט איז מו מאטונימנוטוו וווטם | עופ מווע נט  |            |           |
|              |            |   |                              |  |            |           |
|              |            |   |                              |  |            |           |
|              |            | Highlights:   |                              |  |            |           |
|              |            |   | ning Sustam The CD Leb       | Convoyoria   |            |           |
|              |            | <ul> <li>A compact Industry 4.0 Learn<br/>"ready for Industry 4.0" bec</li> </ul> |                              |  |            |           |
|              |            | electrical interfaces as well a   |                              |  |            |           |
|              |            | A modular and flexible layou  |                              |  |            |           |
|              |            | makes working in various lea  |                              |  |            |           |
|              |            | transfer system with an integ<br>production system with clou                      |                              | cross-linked   |            |           |
|              |            | Modern industry supervision   |                              | lar controller S7  |            |           |
|              |            | 1512SP makes the system a   |                              |  |            |           |
|              |            | • The learning content is part  |                              |  |            |           |
|              |            | application modules are mo  |                              |  |            |           |
|              |            | via I/O, Profinet, TCP/IP, OP<br>the type of the module.                          | C UA or Plug & Produce -     | depending on   |            |           |
|              |            | the type of the module.   |                              |  |            |           |
|              |            |   |                              |  |            |           |
|              |            | Learning content for project work:  |                              |  |            |           |
|              |            | Installation and structure of   | manufacturing plants         |  |            |           |
|              |            | Capture of information using  |                              |  |            |           |
|              |            | PLC programming   |                              |  |            |           |
|              |            | Control via embedded control  | ollers*                      |  |            |           |
|              |            | Communication based on op   |                              |  |            |           |
|              |            | Industrial communication an   | nd IT-security*              |  |            |           |
|              |            | Fieldbus technology   |                              |  |            |           |
|              |            | Identification systems  | <b>a</b>                     |  |            |           |
|              |            | Plug & Produce: Quick modi  | fication*                    |  |            |           |
|              |            | Cyber-physical systems*     Droduction monogement with                            | h MECK. Cuastien mere        | zomont   |            |           |
|              |            | <ul> <li>Production management wit<br/>controlling and visualization</li> </ul>   |                              | gement,  |            |           |
|              | 1          |   |                              |  |            |           |



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| Position    | Quantity | Description  |                        |            |         |
|             |          | Use of the cloud technology*   |                        |            |         |
|             |          | (* These topics require additional products)   |                        |            |         |
|             |          | Main components:   |                        |            |         |
|             |          | • Mono-belt transfer system length 700 mm, width   | n 80 mm                |            |         |
|             |          | Pallet stopper with sensors and valve  |                        |            |         |
|             |          | Pallet identification BCD with 4 inductive sensors     Pallet identification PCD on 1/0 kink                         | 5                      |            |         |
|             |          | <ul> <li>Pallet identification RFID on I/O-Link</li> <li>Capacitive sensor at the beginning and the end o</li> </ul> | of the convoyor        |            |         |
|             |          | <ul> <li>PLC Siemens S7-1500 CPU 1512SP</li> </ul>   | in the conveyor        |            |         |
|             |          | <ul> <li>16 inputs/16 outputs digital 24 V</li> </ul>  |                        |            |         |
|             |          | Siemens I/O-Link Master  |                        |            |         |
|             |          | • Festo I/O-Link Device 8 inputs/8 outputs digital, outputs analogue   | 4 inputs/2             |            |         |
|             |          | Incremental position measuring via optical sense   | or                     |            |         |
|             |          | Conveyor drive 24 VDC  |                        |            |         |
|             |          | DC motor controller bi-directional and creep spee  |                        |            |         |
|             |          | I/O interface for application module Syslink 8 inp   | •                      |            |         |
|             |          | Interface for control panel with 4 inputs/4 output Stop  | ts and Emergency       |            |         |
|             |          | Note: The optional touch panel and the application module this item.   | es are not included in |            |         |



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| Position    | Quantity | Description   |   |   |            |            |
| Pos. 2      | 4,00     | CP Lab Touch panel Sieme<br>D12605<br>Description<br>The CP Lab Touch Panel TF<br>monitoring. Thus, the cont<br>actuators and lamps also a<br>functionality. The touch pa<br>The Human Machine Interf<br>classical buttons and lamp<br>I/O cable and is used as co<br>HMI case is mounted on th<br>configuration, the HMI cas<br>indicators. If required, the | P700 Comfort is used for operator co<br>rol panel includes in addition to the<br>Siemens Touch Panel TP700 Comfo<br>nel is complete integrated, wired an<br>face (HMI) consists of a case and a co<br>is. It is plugged to the CP Lab Conveyontrol panel for signal entry and mor<br>e profile frame of the conveyor. In the<br>is equipped with 4 electrical actua<br>HMI case can be equipped with add<br>p to 8 potential-free switching conta | classical<br>ort with high-end<br>nd tested.<br>onsole with<br>yor by means of<br>nitoring unit. The<br>he basic<br>itors and 4 light<br>itional 8 electrical |            | re similar |
|             |          | <ul> <li>High-end function<br/>showing plant do</li> <li>Data backup</li> <li>Different interfact</li> <li>Integrated PROFICE</li> </ul>  | lay with 16 Mio. colours and LED ba<br>nality: Archiving, VB-script and varic<br>ocumentation (i.e. as PDF) or as web<br>es for process communication<br>NET-Switch<br>m WinCC Comfort V11 (TIA Portal)   | ous viewers for   |            |            |
|             |          |   | Pixel x 480 Pixel<br>rs: 16 Mio.<br>aces<br>ace<br>with integrated switch<br>H x T): 214 x 158 x 70 mm<br>24 V DC   |   |            |            |
|             |          | <ul> <li>Process coupling:</li> <li>\$7-1200, \$7-150</li> <li>\$7-200, \$7-300/</li> </ul>   |   |   |            |            |



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| osition     | Quantity | Description  |   |                     |            |         |
| osition     |          | <ul> <li>LOGO!</li> <li>WinAC</li> <li>Allen Bradle</li> <li>Allen Bradle</li> <li>Mitsubishi (</li> <li>Mitsubishi (</li> <li>OMRON (Ho</li> <li>Modicon (M</li> <li>Modicon (M</li> <li>OPC UA Clie</li> <li>Main components of the second s</li></ul> | (MC TCP/IP)<br>(FX)<br>ost Link)<br>Nodbus TCP/IP)<br>Nodbus RTU)<br>ent<br>the HMI case<br>d<br>ctuators<br>tors<br>stop<br>ting plate<br>m        |                     |            |         |
|             |          | <ul> <li>Cable set</li> <li>System requirements</li> <li>64 Bit: Wind<br/>8.1 Professi</li> </ul>  | or control panel (extended configura<br>::<br>dows 7 Professional, Enterprise, Ultin<br>ional, Enterprise<br>dows 7 Professional, Enterprise, Ultin | nate SP1, Windows   |            |         |
|             |          | Ethernet cal   | uch Panel TP700 Comfort<br>ble (CAT 6, crossover, 6 m)<br>g-, Options- and Runtime software and<br>TIA-Portal)                                      | d license WinCC     |            |         |
|             |          | educational purposes   | quires a license for the end user to b<br>s. Festo provides the declaration text<br>declaration or does not deliver it on<br>s product.             | on a form. If Festo |            |         |



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| Position     | Quantity   | Description  |                                    |         |           |
| Pos. 3       | 4,00       Switch XB008         D12725       D12725         SCALANCE XB008 unmanaged Industrial Ethernet Switch for 10/100 Mbit / s;<br>LED diagnostics, IP20, DC 24V power supply, with 8x 10/100 Mbit / s twisted pair ports with RJ45 sockets;         Note: this unmanaged switch is not for advanced network scenarios such as ring high availability, VLAN operation, and others. suitable. We are happy to advise you on further variants for the implementation of these topics. |  | s twisted<br>s such as<br>happy to |         |           |
| Pos. 4       | 4,00   | Edutrainer         159396         Power supply unit for mounting frame         • Input voltage: 85 – 265 V AC (47 – 63 Hz)         • Output voltage: 24 V DC, short-circuit-proof         • Output current: max. 4 A         • Dimensions: 170 x 240 x 92 mm         Type: Connector as per CEE 7/VII for DE, FR, NO, SE, FI, PT, ES, AT, N         TR, IT, DK, IR, ID | IL, BE, GR,                        | Picture | e similar |



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| osition            | Quantity  | Description  |  |              |               |           |
|                    |           |  |  |              |               |           |
| CP Appli<br>Pos. 5 | ication m | ODULES   |  |              |               | -         |
| 00.9               | 1,00      |  |  |              | -             |           |
|                    |           | D13007   |  |              | in the second | THE N     |
|                    |           |  |  |              | 14 . III      |           |
|                    |           | Function   |  |              | H.C.          |           |
|                    |           | The application module Magazine ca<br>as well as on CP Lab conveyors. It is        |  |              |               |           |
|                    |           | cubic workpieces. The workpieces ar  | e stored in a magazine shaft             | and can be   |               | /         |
|                    |           | distributed individually depending of actuators are connected to an I/O terms      |  |              |               |           |
|                    |           | by fieldbus nodes (Profinet I/O). The assembled and tested.                        | application module is compl              | etely        | Pictur        | e similar |
|                    |           | assembled and tested.  |  |              |               |           |
|                    |           | Learning content:  |  |              |               |           |
|                    |           | Leaning content.   |  |              |               |           |
|                    |           | Mechanical and electrical d  | esign of the module                      |              |               |           |
|                    |           | <ul> <li>Electro pneumatic circuits</li> <li>Pneumatic drive technology</li> </ul> | 4  |              |               |           |
|                    |           | <ul> <li>Fieldbus technology</li> </ul>  | y  |              |               |           |
|                    |           | Sensor technology  |  |              |               |           |
|                    |           | <ul> <li>PLC programming</li> <li>Magazining and distributin</li> </ul>            | g of parts                               |              |               |           |
|                    |           | <ul> <li>Variable manufacturing</li> </ul>   |  |              |               |           |
|                    |           | Communication with super   | ior control and MES                      |              |               |           |
|                    |           | Consisting of:   |  |              |               |           |
|                    |           | • 1x Module frame made from  | n aluminium profiles                     |              |               |           |
|                    |           | • 1x Stacking magazine   | ·· ·····                                 |              |               |           |
|                    |           | 1x Pneumatic feed separator  |  |              |               |           |
|                    |           | <ul><li>1x Valve block</li><li>1x Signal interface</li></ul>                       |  |              |               |           |
|                    |           | U U U U U U U U U U U U U U U U U U U  |  |              |               |           |
|                    |           | Technical data   |  |              |               |           |
|                    |           | Interface  | SysLink IEEE488, 24 pin                  |              |               |           |
|                    |           | Number of I/O<br>Voltage   | 8 DI/8 DO<br>24 VDC                      |              |               |           |
|                    |           | Pressure<br>Dimensions (H x W x D)   | 6 bar<br>525 mm x 340 mm x 185 r         | nm           |               |           |
|                    |           | Size of workpiece (L x W)  | 115 mm x 80 mm                           |              |               |           |
|                    |           | Magazine   | Stacking magazine<br>Capacity: 10 pieces |              |               |           |
|                    |           | Sensors  | End position detection                   |              |               |           |



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| Position     | Quantity | Description   |  |                   |            |         |  |  |
|              |          |   |  |                   |            |         |  |  |
| Pos. 6       | 1,00     | APPLICATION MODULE MEASURI  | NG   |                   | _          |         |  |  |
|              |          | D13019  |  |                   |            |         |  |  |
|              |          |   |  |                   |            |         |  |  |
|              |          | Function  |  |                   |            |         |  |  |
|              |          | modules as well as on CP Lab conv<br>mounted on adjustable stands and<br>measurement of workpieces at 2 d<br>connected to an I/O terminal, whic   | cation module measuring can be mounted on CP Factory basic<br>as well as on CP Lab conveyors. Two laser distance sensors are<br>on adjustable stands and are used for analogue differential<br>ment of workpieces at 2 different measuring points. The sensors are<br>d to an I/O terminal, which can optionally be exchanged by fieldbus<br>ofinet I/O). The application module is completely assembled and |                   |            |         |  |  |
|              |          | Learning content:   |  |                   |            |         |  |  |
|              |          | <ul> <li>Mechanical and electrica</li> <li>Analog measurement tec<br/>and relative measuremen</li> <li>Fieldbus technology</li> <li>Sensor technology</li> <li>PLC programming</li> <li>Communication with sup</li> </ul> | hnology: Differential mea<br>It  | surement/absolute |            |         |  |  |
|              |          | Consisting of:  |  |                   |            |         |  |  |
|              |          | <ul> <li>1x Module frame made fr</li> <li>2x Laser distance sensor</li> <li>2x Measurement stand</li> <li>1x Signal tower, 3 colours</li> <li>1x Signal interface</li> </ul>  |  |                   |            |         |  |  |
|              |          | Technical Data  |  |                   |            |         |  |  |
|              |          | Interface analogue<br>Voltage<br>Dimensions (H x W x D)<br>Size of workpiece (L x W)<br>Measuring range<br>Measuring accuracy<br>Measuring signal   | Analogue terminal<br>2 Inputs<br>24 VDC<br>775 mm x 240 mm x<br>115 mm x 80 mm<br>10 - 80 mm<br>Max. 0,2 mm<br>0 - 10 V  | : 255 mm          |            |         |  |  |



| 195586     Position   Quantity     Pos. 7   1,00 | Worldskills Lyon 2024 – System Workplace   | 125.138  | 17.03.2023 | 16 / 39   |
|--|--|--|------------|-----------|
| - ,  | Description  |  |            |           |
| Pos. 7 1,00                                      |  |  |            |           |
|  | <ul> <li>APPLICATION MODULE IDRILLING D13013</li> <li>Function The application module iDrilling can be mounted on CP Fact as well as on CP Lab conveyors. It is designed for handling c Two drilling spindles, moving in Z-direction as well as in X-d the drilling process of two pairs of drilling holes in the work, and actuators are connected to an integrated PLC with web- makes the module an intelligent module with CPS functional module is completely assembled and tested.</li> <li>Highlights: <ul> <li>Controller with web interface for Cyber-Physical-Spintegrated intelligent controller supervises the opposingle actuators and is able to automatically gene proposals, e. g. for spare materials, via web interface</li> <li>Compact and powerful Festo controller – With its i Festo CECC-S offers 12 digital inputs, 8 digital out speed digital inputs. Furthermore, a wide range of available: 4x IO Link Master; 1x IO Link Device; 1x 1x CANopen.</li> <li>Autonomous system – A comprehensive CoDeSys enables the autonomous control (stand-alone) and automation of the system.</li> <li>Hybrid control – Direct control of electric and pneu CANopen and IO Link Master.</li> <li>Various communication: ProfiNet; Ethernet IP; Mo</li> </ul> </li> <li>Learning content: <ul> <li>Mechanical and electrical design of the module</li> <li>Electro pneumatic circuits</li> <li>Pneumatic drive technology</li> <li>Electrical drive technology</li> <li>Fieldbus technology</li> <li>Sensor technology</li> <li>PLC programming</li> <li>Handling technology</li> <li>Cyber-Physical-System (CPS): local intelligence an Variable manufacturing</li> <li>Communication with superior control and MES</li> </ul> </li> </ul> | of cubic workpieces.<br>irection, simulate<br>piece. All sensors<br>interface. This<br>dity. The application<br>ystem (CPS) – The<br>erating status of<br>rate order<br>ace.<br>ndustrial design,<br>puts and 2 high-<br>interfaces are<br>Ethernet; 1x USB;<br>function library<br>d economical<br>umatic drives using<br>dbus TCP. | Picture    | e similar |



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| 195586            | Worldskills Lyon 2024 – System | Workplace          | 125.138                                      | 17.03.2023 | 17 / 39 |
| Position Quantity | Description                    |                    | ·  |            |         |
|                   | ,                              | ated linear X-axis | d position senso<br>d position senso<br>2 mm |            |         |



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|--------------------|------------------|---|--|--------------|------------|---------|--|
| 195586             |                  | Worldskills Lyon 2024 – System Wor  | kplace   | 125.138      | 17.03.2023 | 18 / 39 |  |
| Position           | Quantity         | Description   |  |              |            |         |  |
| Position<br>Pos. 8 | Quantity<br>1,00 | APPLICATION MODULE WORKPIECE<br>D13018<br>Function<br>The application module workpiece of<br>modules as well as on CP Lab convey<br>system and is used to output cubic w<br>and actuators are connected to an I/0   | CE OUTPUT<br>output can be mounted on CP Factory basic<br>reyors. It is equipped with a two-axis handling<br>tworkpieces on two roller slides. All sensors<br>I/O terminal, which can optionally be<br>inet I/O). The application module workpiece<br>orkplace for picking workpieces. The<br>assembled and tested.<br>I design of the module<br>motor |              |            |         |  |
|                    |                  | Consisting of:<br>1x Module frame made from<br>1x Handling module<br>1x Parallel gripper, pneuma<br>2x Roller slide<br>1x Valve block<br>1x Signal interface<br>Technical data<br>Interface digital<br>Number of I/O<br>Voltage<br>Pressure<br>X-axis<br>Z-axis<br>Gripper<br>Dimensions (H x W x D)<br>Size of workpiece (L x W) |  | mm           |            |         |  |



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| 195586      |          | Worldskills Lyon 2024 – System Workplace  | 125.138           | 17.03.2023 | 19 / 39   |
| Position    | Quantity | Description   |                   |            |           |
| Pos. 6      | 1,00     | CAMERA SYSTEM   |                   |            | -         |
|             |          | 8158958   |                   | 1          | <b>1</b>  |
|             |          |   |                   |            |           |
|             |          | Machine Learning in Image Processing  |                   | 1          | 1         |
|             |          |   |                   |            |           |
|             |          | The MPS IoT Kit Machine Learning deals with machine learning language networks ("deep learning"), one of the most prominent sub-disc  |                   | Dictur     | e similar |
|             |          | artificial intelligence. The hardware includes a single-board com<br>with an HD camera to capture images that are then analysed by    | puter equipped    | Tictur     | e sinnai  |
|             |          | network.  |                   |            |           |
|             |          | A variety of Python programmes are available as software. The f   |                   |            |           |
|             |          | almost all tools are web-based, so that access via mobile device<br>smartphones, tablets, laptops, etc. is possible. Thanks to the W  |                   |            |           |
|             |          | MPS IoT Kit Machine Learning offers wireless remote access. The   | e system is       |            |           |
|             |          | delivered ready to use so that learners can start their first exper immediately.  | iments            |            |           |
|             |          | ,   |                   |            |           |
|             |          | The aim of the MPS IoT Kit Machine Learning is for learners to le   |                   |            |           |
|             |          | topics in machine vision with machine learning in a simple way.<br>two learning methods supervised and unsupervised machine lea       |                   |            |           |
|             |          | discussed, but also the main applications in machine vision - i.e classification, object localisation and multiple object recognition |                   |            |           |
|             |          | presented and discussed through a series of hands-on experime   |                   |            |           |
|             |          |   |                   |            |           |
|             |          | Learners will be able to distinguish apples from lemons or tools  | from shoes, etc.  |            |           |
|             |          |   |                   |            |           |
|             |          | A possible task for integration into a learning factory is to check<br>of chutes with workpieces by applying machine learning technic |                   |            |           |
|             |          | all kinds of objects can be recognised and localised. In addition,  | powerful          |            |           |
|             |          | neural network architectures such as so-called convolutional ne are used.   | ural networks     |            |           |
|             |          |   |                   |            |           |
|             |          | All software is well documented and enables learners to conduc<br>machine vision experiments outside the learning factory. Prior p    |                   |            |           |
|             |          | knowledge is not required. The learning materials encourage lea   |                   |            |           |
|             |          | transfer their knowledge to new applications.   |                   |            |           |
|             |          | Learning content  |                   |            |           |
|             |          | Artificial intelligence/machine learning in image proce   | ssing             |            |           |
|             |          | Practical application of convolutional neural networks  | -                 |            |           |
|             |          | Supervised and unsupervised machine learning  |                   |            |           |
|             |          | <ul> <li>Computer vision (image classification, object localisati detection)</li> </ul>   | ion, multi-object |            |           |
|             |          | IoT retrofitting of legacy systems  |                   |            |           |
|             |          | Demofite  |                   |            |           |
|             |          | Benefits  |                   |            |           |





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| 195586      |          | Worldskills Lyon 2024 – System Workplace  | 125.138        | 17.03.2023 | 21 / 39   |
| Position    | Quantity | Description   | ł              |            | 4         |
| Pos. 11     | 4,00     | CARRIAGE<br>D12720  |                | 0          | 1         |
|             |          | Description<br>The carriage makes the CP Lab system into a compact and mobile<br>Lab conveyor can be easily mounted on the carriage.  | e unit. The CP |            |           |
|             |          | The carriage is designed for the use of CP Lab conveyor and is su combination with CP Factory.  | itable for the | Pictur     | e similar |
|             |          | The carriage will be delivered including rollers and adjustable feet.   |                |            |           |
|             |          | Technical data:   |                |            |           |
|             |          | <ul> <li>Dimensions (H x W x D): 800 mm x 540 mm x 350 mm</li> <li>Frame: A4 in undercarriage</li> </ul>  |                |            |           |
| Pos. 12     | 4,00     | Door for carriage D12720  |                |            |           |
|             |          | D12724<br>Transparent doors for CP Lab carriage D12720.   |                |            |           |
| Pos. 13     | 4,00     | WORKPIECE CARRIER   |                | , i        |           |
|             |          | D12703<br>Description<br>The workpiece carrier is used to transport workpieces or pallets v<br>workpieces on CP Lab or CP Factory pallet transfer systems. For id<br>the workpiece carrier is equipped with a RFID-tag and 4 bit code.<br>Technical data: |                | Pictur     | e similar |
|             |          | <ul> <li>Design: Glass fiber reinforced plastic (GRP)</li> <li>Dimensions: 100 mm x 160 mm x 15 mm</li> <li>BCD Code: codeable, 4 screws</li> <li>Track width: 80 mm</li> <li>Transport weight: max. 3 kg</li> </ul>                                      |                |            |           |



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| 195586       |          | Worldskills Lyon 2024 – System Workplace   | 17.03.2023                              | 22 / 39 |           |
| Position     | Quantity | Description  |   |         |           |
| Pos. 14      | 4,00     | PALLET         D12704         Description         The pallet is used to transport workpieces on CP Lab or CP transfer systems. The pallet, on which the workpiece is transfer workpiece carrier (D12703).         Technical data:         • Design: Aluminium         • Dimensions: 100 mm x 160 mm x 5 mm         • Workpiece holder: changeable, screwed   | Factory pallet<br>nsported is placed on |         | e similar |
| Pos. 15      | 12,00    | WORKPIECE FRONT COVER BLACK         D12705         Description         The workpiece set, consisting of a back cover, printed circul component and front cover, is used for the representation of process steps such as milling, drilling, marking, tempering, assembling, loading, pressing and more.         The front cover is part of the workpiece set.         Technical data:         • Material: Plastic, black         • Dimensions: 110 mm x 60 mm x 10 mm | of many relevant                        | Pictur  | e similar |



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|---|------|---|---------------|------------|-----------|--|--|
| 195586  |      | Worldskills Lyon 2024 – System Workplace  | 125.138       | 17.03.2023 | 23 / 39   |  |  |
| Position Quantity   |      | Description   |               |            |           |  |  |
| Pos. 16   | 4,00 | WORKPIECE FRONT COVER GREY  |               |            |           |  |  |
|   |      | D12709  |               |            |           |  |  |
|   |      |   |               |            |           |  |  |
|   |      | Description   |               | Pictur     | e similar |  |  |
| component and front cover, is used<br>process steps such as milling, drilling |      | The workpiece set, consisting of a back cover, printed circuit b<br>component and front cover, is used for the representation of n<br>process steps such as milling, drilling, marking, tempering, tes<br>assembling, loading, pressing and more. | nany relevant |            |           |  |  |
|   |      | The front cover is part of the workpiece set.   |               |            |           |  |  |
|   |      | Technical data:   |               |            |           |  |  |
|   |      | <ul> <li>Material: Plastic, grey</li> <li>Dimensions: 110 mm x 60 mm x 10 mm</li> </ul>   |               |            |           |  |  |
| Pos. 17   | 4,00 | WORKPIECE FRONT COVER BLUE D12711   |               |            |           |  |  |
|   |      |   |               |            |           |  |  |
|   |      | Description   |               | Pictur     | e similar |  |  |
|   |      | The workpiece set, consisting of a back cover, printed circuit b<br>component and front cover, is used for the representation of n<br>process steps such as milling, drilling, marking, tempering, tes<br>assembling, loading, pressing and more. | nany relevant |            |           |  |  |
|   |      | The front cover is part of the workpiece set.   |               |            |           |  |  |
|   |      | Technical data:   |               |            |           |  |  |
|   |      | <ul> <li>Material: Plastic, blue</li> <li>Dimensions: 110 mm x 60 mm x 10 mm</li> </ul>   |               |            |           |  |  |
|   |      |   |               |            |           |  |  |



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|                        |          | Worldskills Lyon 2024 – System Workplace  | 125.138      | 17.03.2023 | 24 / 39   |
| Position               | Quantity | Description   |              |            |           |
| Pos. 18                | 4,00     | WORKPIECE FRONT COVER RED   |              |            |           |
|                        |          | D12713  |              |            |           |
|                        |          |   |              |            |           |
|                        |          | Description   |              | Pictur     | e similar |
|                        |          | The workpiece set, consisting of a back cover, printed cir<br>component and front cover, is used for the representatio<br>process steps such as milling, drilling, marking, temperir<br>assembling, loading, pressing and more. |              |            |           |
|                        |          | The front cover is part of the workpiece set.   |              |            |           |
|                        |          | Technical data:   |              |            |           |
|                        |          | <ul> <li>Material: Plastic, red</li> <li>Dimensions: 110 mm x 60 mm x 10 mm</li> </ul>  |              |            |           |



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| 195586      |          | Worldskills Lyon 2024 – System Workplac   | .e 1   | 25.138                   | 17.03.2023 | 25 / 39   |
| Position    | Quantity | Description   |  |                          |            |           |
| Pos. 15     | 1,00     | FactoryViews MES4 V3 for CP Lab   |  |                          |            |           |
|             |          | D15005 -S-  |  |                          |            |           |
|             |          | Description:  |  |                          | у,         | e similar |
|             |          | The MES4 V3 controls production orders i<br>and takes on a central software function i<br>combines classic MES functionalities with<br>growing interconnected networks in the Ir<br>MES4 V3 is specifically focused on educat | n manufacturing. The MES4<br>the new opportunities offend<br>ndustrial Internet of Things. | 4 V3<br>ered by the<br>· |            |           |
|             |          | perfect for use in training and teaching co<br>relevant functions can be accessed quickl<br>based user interface.   | urses in industrial automat  | tion. All                |            |           |
|             |          | FactoryViews MES4 V3 supports CP Lab a  | nd MPS 400 systems.  |                          |            |           |
|             |          | The function range includes:  |  |                          |            |           |
|             |          | Graphical system configurator w   | vith station library   |                          |            |           |
|             |          | <ul> <li>Graphical workplan editor, inclu<br/>consumption</li> </ul>  | ding processing time and e   | nergy                    |            |           |
|             |          | Production control via service-or   | riented architecture (SOA)   |                          |            |           |
|             |          | Communication with resources v  | via TCP/IP or OPC UA   |                          |            |           |
|             |          | Order management  |  |                          |            |           |
|             |          | Graphical live tracking of workpl   | lan steps  |                          |            |           |
|             |          | Operator view with status indication  | tor per resource   |                          |            |           |
|             |          | • Reporting of S7 PLC warnings ar   | 1d errors  |                          |            |           |
|             |          | • Editor for database analyses, e.  | g. OEE or quality, with live o   | diagrams                 |            |           |
|             |          | Import and export functions for<br>evaluations in standard formats  | •  | rders and                |            |           |
|             |          | Layout export to CIROS  |  |                          |            |           |
|             |          | • Software languages: DE, EN, FR,   | , PT, HU, ZH   |                          |            |           |
|             |          | • Interfaces: TCP/IP, REST, SQL   |  |                          |            |           |
|             |          | Thanks to its integration with FactoryView<br>seamless interaction with other apps such<br>platform-independent operation, and the<br>statuses to be backed up and restored to  | h as our educational websh<br>snapshot function, which a                                   | iop,                     |            |           |



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| 195586           | Worldskills Lyon 2024 – System Workplace   | 125.138  | 17.03.2023 | 26 / 39   |
| Position Quantit | <ul> <li>Description</li> <li>Scope of delivery:         <ul> <li>MES4 V3 software for CP Lab, single license The software can be accessed from multiple web be local network.</li> <li>PC with TFT-monitor</li> <li>If the software is the softwa</li></ul></li></ul> | rowsers within the   |            |           |
| Pos. 16 1,00     | Web shop for MES4           D17012           Modern web shop for ordering configurable product variants           The product properties selected by the online ordering party from the Web shop to the Manufacturing Execution System Mensures and monitors the production in the plant.           Course contents:           Industry 4.0           ERP functions examples           Configuration of a webshop           MES connection           The customer can place orders via the webshop running on t browser is necessary to access the webshop from PCs or mol as tablets, smartphones or laptops. The customer sees in the order directly the total cost of the cart. The prices for the indiproducts in the different variants are managed.           For sales orders, delivery notes and invoices can be printed or production process with too low stock is also possible. Each product can be configured for the webshop and is then availar shop as a selection.  | are transferred<br>AES4, which then<br>he server. Only a<br>bile devices, such<br>e compilation of his<br>ividual parts of the<br>but. An automated<br>newly defined |            | e similar |



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| 195586       |          | Worldskills Lyon 2024 – System Workplace  | 125.138  | 17.03.2023 | 27 / 39   |
| Position     | Quantity | Description   |  |            |           |
|              |          | Freely configurable<br>Network communication<br>Parallel commissioning of several plants<br>Server with database set up on PC to be ordered separately<br>PC)<br>Communication between web shop and MES<br>Inventory management system<br>Individual pricing of the products<br>Print preview of delivery notes and invoices<br>Large statistics area about orders, sales, customers, country<br>Order via the local network, also possible over the internet w<br>Personalized order<br>Different prices for different variants<br>Indication about availability<br>MES + MES mobile<br>Live view of the order list<br>E-mail dispatch for order tracking<br>The data of the system is stored in a MySQL database, which c<br>accessed via a preinstalled user interface. All data can be expo | overview<br>vith Cloudpaket<br>an be easily                                |            |           |
|              |          | formats (e.g., CSV).  |  |            |           |
| Pos. 17      | 1,00     | Equipment Set TP1312 Smart Sensors  |  |            | <u>_</u>  |
|              | ,        | 8116358   |  |            |           |
|              |          | Equipment Set TP1312 Smart Sensors  |  | Pictur     | e similar |
|              |          | The Equipment Set TP 1312 Smart Sensors includes a basic se<br>sensors with IO-Link® communication: diffuse photoelectric se<br>proximity sensor and ultrasonic sensor. Along with the sensors<br>package includes an IO-Link® master with 4 sensors communi<br>3 different Ethernet protocols (PROFINET®, EtherNet/IP™ or M<br>communicate with programmable logic controllers and other fa<br>automation devices along with all the necessary cables.   | ensor, inductive<br>s, the training<br>cation ports and<br>Aodbus® TCP) to |            |           |
|              |          | All components of TP 1312 are mounted on our Quick-Fix® mo<br>and are compatible with the Sensor Workstation (8110729) or<br>plates.  | ounting system<br>one of our profile                                       |            |           |
|              |          | Features  |  |            |           |
|              |          | Uses the most important smart sensors in Industry 4.0 with a clearning path   | comprehensive  |            |           |
|              |          | <ul> <li>Uses the most important smart sensors in Industry 4 comprehensive learning path</li> <li>Industrial IO-Link® communication master module w Ethernet protocols</li> <li>Enables building IO-Link® communication setups just</li> </ul>  | vith 3 different   |            |           |
|              |          | industry with sensors, IO-Link® master and PLC with<br>smart interface also in the learning experience  |  |            |           |



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| Position     | Quantity | Description   |  |            | •       |
| Position     | Quantity | <ul> <li>Easy to integrate the specific smart sensors you a curriculum</li> <li>Develops new skills for the newest smart sensor</li> <li>Prepares students for further learning in factory a</li> <li>Learning goals</li> <li>Students will follow the scope of the training curriculum fr understanding of Industry 4.0 concepts and sensors funda</li> <li>Then, through a comprehensive learning path, students wiimportant competencies regarding smart sensors and theil Competencies to be developed include:</li> <li>Understanding the benefits of smart sensors in th 4.0</li> <li>Selecting sensors for the right applications</li> <li>Setting up IO-Link® communication and parame in the field</li> <li>Monitoring and analyzing data to perform predic replace defective sensors quickly</li> <li>Integrating smart sensors to programmable logic different manufacturing communication layers</li> <li>Troubleshooting sensors</li> <li>Technical Data:</li> <li>Scope of delivery:         <ul> <li>One (1) inductive proximity sensor with IO-Link (81107)</li> <li>One (1) IO-Link® master module with 4 ports (8</li> <li>One (1) IO-Link® master module with 4 ports (8</li> <li>One (1) accessories kit for Equipment Set TP13' (8112723)</li> <li>Also requires the following accessories (not inclu Workstation (8110723) or a profile plate for Quic system combined with 24 V dc power supply</li> </ul> </li> </ul> | technology<br>automation<br>om an initial<br>amental principles.<br>ill develop the most<br>r benefits in industry.<br>he context of Industry<br>terize smart sensors<br>tive maintenance and<br>c controllers and the<br>(8110725)<br>(® (8110725)<br>(® (8110726)<br>(27)<br>3110729)<br>12 Smart Sensors<br>uded): Sensor |            |         |



| Quantity<br>1,00 | Worldskills Lyon 2024 – System Workplace         Description         Accessories for Smart Sensors         Accessories for TP 1312 consisting of | 125.138   | 17.03.2023  | 29 / 39   |
|------------------|--|---|---|---|
|                  | Accessories for Smart Sensors  |   |   |   |
| 1,00             |  |   |   |   |
|                  | Accessories for TP 1312 consisting of  |   |   |   |
|                  |  |   |   |   |
|                  | • Slide unit 572740  |   |   |   |
|                  | A DECK   |   |   |   |
|                  | • Set of test objects 549830   |   |   |   |
|                  |  |   |   |   |
|                  | • RFID sensor with IO-Link® 8110728  |   |   |   |
|                  |  |   |   |   |
|                  |  |   |   |   |
|                  |  |   |   |   |
|                  |  | <ul> <li>RFID sensor with IO-Link® 8110728</li> </ul> | <ul> <li>RFID sensor with IO-Link® 8110728</li> </ul> | <ul> <li>RFID sensor with IO-Link® 8110728</li> </ul> |



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| 195586       |          | Worldskills Lyon 2024 – System Workplace  | 125.138      | 17.03.2023 | 30 / 39 |
| Position     | Quantity | Description         • Flow sensor with IO-Link® 8115026         Image: Constraint of the sensor with IO-Link® 8115026 |              |            |         |
|              |          | • Systainer® with T-LOC system 8022297  |              |            |         |
|              |          | • Systainer/container insert B 687461   |              |            |         |
|              |          | • Handles for Systainer 683012  |              |            |         |



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| 195586            | Worldskills Lyon 2024 – System Workplace   | 125.138   | 17.03.2023 | 31 / 39   |
| Position Quantity | Description  |   |            |           |
| Pos. 19 1,00      | CIROS 7<br>8140772   |   | Picture    | e similar |
|                   | CIROS 7  |   |            |           |
|                   | CIROS is an industrially tested, extremely powerful platform<br>using 3D simulation models for automation technology. It c<br>following functions into a single common interface:  |   |            |           |
|                   | <ul> <li>Discrete time 3D simulations with modelling mech</li> <li>CAD import filter for STEP, IGES, STL, VRML and CO</li> <li>CAD export filter for conventional formats</li> <li>Layout of systems and production lines based on application modules</li> <li>Access to more than 1100 robot models</li> <li>Robot programming in the following programming others:         <ul> <li>Industrial Robot Language (IRL)</li> <li>Mitsubishi MELFA BASIC V</li> <li>Kuka Robot Language (KRL)</li> <li>ABB Rapid</li> </ul> </li> <li>Connection to the Manufacturing Execution System operating training factories as a didactic digital tw</li> <li>Virtual human with 30 independent degrees of free</li> <li>The extensive model library contains         <ul> <li>Beginner models for an introduction to basic top</li> <li>Further course documents in Festo LX (free regis</li> <li>Virtual illustrations from the Festo Didactic learn MPS and Robotino for transferring learning perfor simulated and physical devices</li> <li>Prepared examples on industrial interfaces such Advanced</li> </ul> </li> <li>The model is either controlled via the integrated S through the use of other interpreters such as IRL of interfaces to PLCSIM and PLCSIM Advanced</li> <li>Additional connections to other OPC-based interfac CODESYS are established using OPC UA or EZOPC</li> <li>EasyPort is used for coupling up to four external h simulation control (hardware in the loop)</li> <li>Matlab, Python or EtherCat is used to connect extr controllers and to model the system behavior</li> <ul> <li>Expandable behaviors for detecting and correcting logged in the fault simulation mode. Evaluation of enables effective training for systematic commissis the event of malfunctions to be organized in the s environment.</li> <li>In order to process the outcomes of exercises and effectively as</li></ul></ul> | OLLADA<br>model libraries and<br>g languages, among<br>m MES4 for<br>vin<br>edom<br>vics<br>stration required)<br>ing systems such as<br>mance between<br>as PLCSIM<br>TEP7 PLC control,<br>or via external<br>aces such as<br>ardware PLCs for<br>ernal simulation<br>g faults can be<br>the outcomes<br>ioning and repairs in<br>imulation<br>projects as<br>id modes are |            |           |



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| Position     | Quantity        | Description   |                                       |            |         |
|              |                 | <ul> <li>Intel Core i5 (7th generation) or equivalent</li> <li>8 GB RAM, at least 200 GB HDD/SSD</li> <li>Windows 10 1709 64-bit or later</li> <li>Simple models: Intel HD 530 or better</li> <li>Complex models or for displaying large models in v<br/>NVIDIA GeForce GTX 1070 or better</li> <li>CIROS supports OpenVR. A free Steam account is ruse the virtual reality feature</li> </ul> The purchase of a license provides the rights to contin the version including two subsequent years of updates Type: CIROS 7: | equired in order to<br>uously operate |            |         |
|              |                 | CIROS configuraton: CIR-DIG-STU-CPL   |                                       |            |         |
|              | 1x Ciros Studio |   |                                       |            |         |
|              |                 | 1x Ciros CP System model library  |                                       |            |         |



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| Position | Quantity | Description   |  |            |           |
| Pos. 20  | 1,00     | Energy measurement box  |  |            |           |
|          |          | 8129208   |  |            |           |
|          |          |   |  | A          |           |
|          |          | The single-phase energy measurement box expands training<br>measuring the consumption of electrical energy and compo-<br>other variables such as currents, voltages, active and react<br>processing the data and communicating via the network. In<br>possibility for energetic analyses and optimizations, this p<br>for a continuous stream of live data from the production pl<br>stations with single-phase electrical consumption as well a<br>consumption can be evaluated in parallel per energy meas<br>three CP Lab belts each with 24 V power pack. | ressed air as well as<br>tive power,<br>n addition to the<br>rovides a data source<br>lant. Up to three<br>as compressed air | Pictur     | e similar |
|          |          | The energy measurement box can be placed both on the tal<br>laboratory trolley, or hung in an A4 holder by removing the<br>supplied via an IEC C14 male connector. This means that th<br>measurement box can be operated flexibly both at various<br>modules as well as at laboratory workstations or other con<br>simply by reconnecting.  | e feet. Power is<br>he energy<br>training factory  |            |           |
|          |          | The single-phase energy measurement box includes the fo<br>Power measurement:   | llowing components:  |            |           |
|          |          | <ul> <li>Siemens SENTRON PAC3220 power analyzer for 3</li> <li>3x current transformer 35:1</li> <li>3x IEC 60320-1 C13 socket, max. 10 A total</li> </ul>   | 3 measuring channels   |            |           |
|          |          | Compressed air measurement:   |  |            |           |
|          |          | <ul> <li>3x Festo SFAH IO-Link flow sensor</li> <li>3x Festo SPAU IO-Link pressure sensor</li> <li>3x In and 3x Out push-in connectors for 6 mm tub</li> </ul>  | bing   |            |           |
|          |          | Control and communication:  |  |            |           |
|          |          | <ul> <li>Festo CPX-E PLC with IO-Link master, web server,</li> <li>RJ45 LAN connection</li> </ul>   | , OPC UA server  |            |           |
|          |          | All constituents are state-of-the-art industrial components<br>the sensors is implemented via Modbus TCP and IO-Link, c<br>energy data management is provided via a documented OF   | communication to the   |            |           |
|          |          | Scope of delivery:  |  |            |           |
|          |          | <ul> <li>Single-phase energy measurement box</li> <li>3x IEC connecting cable</li> <li>Network cable</li> <li>Connections, pneumatic</li> <li>Operating instructions with connection examples</li> </ul>  | 5  |            |           |



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| 195586       |          | Worldskills Lyon 2024 – System Workplace   | 125.138                      | 17.03.2023 | 34 / 39   |
| Position     | Quantity | Description  |                              |            |   |
|              |          | Suitable for: Energy monitoring package for CP systems, including software D35002, IOT Gateway   | PC and                       |            |   |
|              |          | Type: Single-phase energy measurement box  |                              |            |   |
| Pos. 21      | 1,00     | FactoryViews Energy App  |                              |            | mag Hany<br>may a hang<br>Ada hang hang<br>Ada hang hang hang hang hang hang hang han |
|              |          | Energy monitoring is the basis for understanding, controlling and o<br>energy flows within a factory. The energy monitoring package inclu<br>necessary software tools for communication, visualization and and   | udes all                     |            |   |
|              |          | An OPC UA client periodically retrieves energy data from the contro<br>energy measuring box and stores them in an open MariaDB databa  |                              | Pictur     | e similar   |
|              |          | The energy data can be visualized, evaluated and exported as CSV various dashboards and it is possible to actively intervene in produ  |                              |            |   |
|              |          | The Monitoring dashboard offers a graphical visualization of all sig<br>a real-time diagram and historical values. Limit values can be defin<br>signal, and a notification is triggered if the limits are exceeded or u<br>the Smart-Maintenance Option is available, a maintenance order of<br>automatically. | ned for each<br>undercut. If |            |   |
|              |          | The Analysis dashboard allows the graphical analysis of the power<br>consumption of process steps, for example to quantify energy effic<br>measures.   |                              |            |   |
|              |          | The footprint dashboard visualizes the current consumption with c<br>environmental effects. Parameters such as electricity price and spe<br>emissions can be configured.   |                              |            |   |
|              |          | The Factory dashboard allows to start and stop the CP Systems lead<br>to monitor the total consumption, to reduce peak loads and to par<br>energy-efficient operation.   |                              |            |   |
|              |          | In simulation mode, recorded data or random values can be strear of real measurements.   | ned instead                  |            |   |
|              |          | Learning contents:   |                              |            |   |
|              |          | <ul> <li>Industrial energy monitoring with OPC UA</li> <li>Power and compressed air consumption</li> <li>Energy efficiency measures</li> <li>Costs and carbon emissions</li> <li>Dashboard creation</li> </ul>   |                              |            |   |
|              |          | Scope of delivery:   |                              |            |   |
|              |          | <ul> <li>Energy App software, single license<br/>The dashboards can be accessed from multiple web brow<br/>the local network.</li> <li>Connectivity to all signals of one Energy Measurement Be<br/>8129208 or 8130678)</li> <li>Workbook</li> </ul>   |                              |            |   |



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| Position     | Quantity | Description  |  |            |                 |
| Pos. 22      | 1,00     | Wireless Access Point for CP System  |  |            |                 |
|              |          | D14203   |  |            |                 |
|              |          |  |  |            |                 |
|              |          | TP-Link Archer C7 AC1750 Dual Band Gigabit WiFi Router (1<br>450Mbps (2.4GHz), 4 Gigabit LAN Ports, 1 USB 2.0, Print / M<br>APP Control) Black   |  |            |                 |
|              |          |  |  |            |                 |
|              |          | Accespoint is needed for CP System.  |  |            |                 |
| Pos. 23      | 1,00     | IOT GATEWAY  |  | 0          | - ere           |
|              |          | 8172682  |  |            |                 |
|              |          | The IoT Gateway connects production level devices to the Ir<br>Things (IIoT). It has a network connection for the device side<br>side and a hardware switch to control read and write author   | e, one for the cloud                                     |            | Claud<br>Desice |
|              |          | The gateway offers a web interface with configuration optio  | ns, including  | Pictur     | e similar       |
|              |          | <ul> <li>Network configuration including DHCP client</li> <li>NTP client for time synchronization</li> <li>Device management</li> <li>MQTT broker settings</li> </ul>  |  |            |                 |
|              |          | The gateway is able automatically to find known device type<br>Didactic energy measurement box in the network. The infor-<br>the devices is stored in a signature file. After the devices ha<br>referred to as onboarding, the data is automatically retrieve<br>forwarded to an MQTT broker.                          | mation for pairing<br>we been paired,                    |            |                 |
|              |          | Your own signature files can be created and imported, mean<br>device types can be found, coupled and read out via OPC U/   |  |            |                 |
|              |          | The graphical development environment installed on the ga<br>enables edge computing functionalities, i.e. data processing<br>between the local network and the cloud.  |  |            |                 |
|              |          | A wide range of signal sources can be integrated using libra<br>the protocols OPC UA, Modbus TCP or REST API, signals can<br>using function blocks or JavaScript code, dashboards can be<br>visualization and signals can be output to server services su<br>or cloud services such as Siemens MindSphere or Microsoft | n be pre-processed<br>e set up for<br>uch as MQTT, MySQL |            |                 |
|              |          | The gateway can be installed with the supplied accessories carriage or on the NetLab EduTrainer and connected.   | e.g. in CP Lab   |            |                 |
|              |          | Scope of delivery:   |  |            |                 |
|              |          | <ul> <li>IoT Gateway</li> <li>Connection cable 24 VDC to 4 mm safety plug</li> <li>2 x network cable &amp; Mounting accessories</li> <li>Training documents with example scenario</li> </ul>   |  |            |                 |



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| Position    | Quantity | Description  |  |            |           |
| Pos. 24     | 1,00     | TP 1333: networks and IT Security  |  |            |           |
|             |          | 8127829  |  | Q          |           |
|             |          | Equipment set TP 1333: networks and IT Security  |  | Pictur     | e similar |
|             |          | Equipment set TP 1333 contains components for the setup or<br>that serve to communicate all important fundamentals of IT s   |  | , ictai    | e sinnar  |
|             |          | • 2x EduTrainers with integrated electricity supply an<br>router and XC208 switch  | nd one each of S615  |            |           |
|             |          | • 1x Ethernet cable set  |  |            |           |
|             |          | 1x Festo NetLab Toolkit configuration software   |  |            |           |
|             |          | 1x configuration files for the exercises with S615 ro<br>switch  |  |            |           |
|             |          | • 1x workbook, in printed form and on a USB data ca  | rrier  |            |           |
|             |          | The equipment is configured for two workstations. The indivi<br>be adapted to the spatial situation in the classroom or labora<br>can be positioned flexibly to solve the exercises: on worktabl<br>mounting frame. The two EduTrainers with Siemens router at<br>core of equipment set TP 1333.   | atory. The modules<br>les or in an A4                                      |            |           |
|             |          | The enclosed Festo NetLab Toolkit (NLTK) configuration softw<br>configuration of network and safety functions. Examples of s<br>include setting an IP address, clearing the ARP address mem<br>and deleting NetLab hierarchy certificates. The NLTK requires<br>rights when launched, and makes the necessary functions av<br>students. During the teaching unit, there is no further need to<br>administrator password.                                 | uch functions<br>ory, and importing<br>s one-off admin<br>⁄ailable to the  |            |           |
|             |          | The enclosed workbook contains detailed practical exercises<br>that are becoming increasingly important in the industry. The<br>foundations supplement the exercises perfectly. Pre-configur<br>setups and sample solutions optimize laboratory-based learn<br>4 can be carried out separately at one workstation. Exercises<br>out jointly at neighboring workstations. The workbook covers<br>cyber security topics in everyday industrial situations: | eoretical<br>red software<br>ning. Exercises 1 to<br>5 5 and 6 are carried |            |           |
|             |          | <ul> <li>switching and monitoring</li> <li>address allocation in production networks</li> </ul>  |  |            |           |
|             |          | <ul> <li>routing and firewall functions</li> <li>VLAN-separated manufacturing networks</li> </ul>  |  |            |           |
|             |          | Network Address Translation (NAT)  |  |            |           |
|             |          | Virtual Private Networks (VPN)   |  |            |           |
|             |          | For schools and training institutions in the commercial sector   | r.   |            |           |
|             |          | The end customer must confirm a license statement that the   |  |            |           |
|             |          | be used for educational purposes. Festo provides the text on<br>customer does not submit this statement, or fails to do so wi<br>time, Festo is not obligated to deliver these goods.  | a form. If the end   |            |           |
|             |          | Type: en   |  |            |           |



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| Position               | Quantity | Description   |  |                                       |                |            |           |  |
| Pos. 25                | 1,00     | Festo LX  |  |                                       |                |            |           |  |
|                        |          | 8133287   |  |                                       |                |            |           |  |
|                        |          | Digital Learning Portal Festo LX – Voucher for 5 users for 1 year   |  |                                       |                |            |           |  |
|                        |          | Festo LX Bas  | ic Subscription  |                                       |                | Pictur     | e similar |  |
|                        |          | Festo LX is our Digital Learning Portal for individual Learning Experiences. Our cloud-based learning portal offers didactically prepared learning content for many technical areas.  |  |                                       |                |            |           |  |
|                        |          | Festo LX is based on multimedia Learning Nuggets that can be combined to form individual Courses and Learning Paths. Courses can thus be adapted very easily and perfectly tailored to the individual needs of teachers and learners.                                     |  |                                       |                |            |           |  |
|                        |          | courses to fa<br>mapping of t   | to LX offers a mix of stand-alone courses and learning equipment-based<br>rses to facilitate the hands-on experiments in technical fields. Festo LX has a<br>oping of the courses with the hardware equipment so you can easily see the<br>rses related to an equipment or the equipment required in a course. |                                       |                |            |           |  |
|                        |          | Overview of content on Festo LX   |  |                                       |                |            |           |  |
|                        |          | On Festo LX, you will find a variety of learning content for many areas of technical education and professional qualification. From factory automation and fluid power to IIoT and Industry 4.0, electrical engineering, process automation, renewable energies and STEM. |  |                                       |                |            |           |  |
|                        |          | Your license gives you access to more than:   |  |                                       |                |            |           |  |
|                        |          |   | 0 eLab courses - digital, interactive co<br>h our Festo Didactic learning systems  |                                       | combination    |            |           |  |
|                        |          |   | eLearning courses to acquire theoreti<br>ed for any hardware   | cal knowledge v                       | vithout the    |            |           |  |
|                        |          |   | 0 Evaluations for knowledge checks b   |                                       |                |            |           |  |
|                        |          |   | courses and simulations for Connecte<br>es FACET and Tec2Screen  | ed Learning with                      | our product    |            |           |  |
|                        |          | • 70  | Short videos and user manuals  |                                       |                |            |           |  |
|                        |          |   | D eBooks, which are PDF versions of w<br>stems   | vorkbooks for yo                      | ur learning    |            |           |  |
|                        |          | Functional s  | соре   |                                       |                |            |           |  |
|                        |          |   | sto LX Basic subscription you will hav<br>and the following features:  | e access to a va                      | riety of Festo |            |           |  |
|                        |          | • Eas   | urse library to browse and filter all ava<br>sy creation and editing of individual co<br>er Management: organize individual lo<br>er permissions, assign specific conten   | ourses with the l<br>earners and grou | _X Creator     |            |           |  |



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|                        |          | Worldskills Lyon 2024 – System Workplace  | 125.138  | 17.03.2023 | 38 / 39 |
| Position               | Quantity | Description         • Tracking of learner's progress and success as well as learning results         • Management and inventory of learning equipment         • Availability of learning portal interface as well as cont languages         • Mobile learning from various devices possible         Individualization of content         With the help of the LX Creator which is included in your license customize Festo Didactic courses according to your needs. You custom content from scratch or integrate existing material into can reuse content from Festo in your own courses to build your individual learning contents. | ents in various<br>e, it is possible to<br>can create<br>Festo LX. You |            |         |
|                        |          | Content on Festo LX<br>Our Festo LX Basic Package supports, amongst others, the following topics:<br>Fluid Power:<br>Various courses for the field of pneumatics, electropneumatics, hydraulics,<br>electrohydraulics and mobile hydraulics   |  |            |         |
|                        |          | Electrical Engineering and Electric Power Technology:<br>Various courses for the field of electrical engineering/electroni<br>circuits, digital electronics, electric drive technology, motor cor<br>mobility   |  |            |         |
|                        |          | Factory and Process Automation:<br>Various courses for the field of mechatronics, sensors and sma<br>industrial control technology, micro controllers, PLC and fieldbu<br>robotics, process instrumentation and control, and water mana   | us technology,   |            |         |
|                        |          | Ilot and Industry 4.0:<br>Various courses for the field of digitalization and networking, d<br>MES and production planning, energy management and monito<br>Intelligence, NX/MCD  |  |            |         |
|                        |          | Sustainability:<br>Various courses for the field of energy efficiency, renewable en<br>generation, biologization  | ergies, power  |            |         |
|                        |          | Metal Working and Mechanics:  |  |            |         |



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| Position               | Quantity | Description  |                      |            |         |
|                        |          | Various courses for the field of turning, milling, drilling, CNC r<br>dimensional metrology. mechanical drives, piping, wiring   | machining, CAD,      |            |         |
|                        |          | Organization and People:   |                      |            |         |
|                        |          | Various courses for the field of lean management, production optimization as well as project management  | n processes and      |            |         |
|                        |          | Licensing and subscription duration  |                      |            |         |
|                        |          | Your license allows you to add an unlimited number of learners<br>organization. Content is accessible to the number of learners<br>license. A license can be withdrawn from one user and assign<br>(transferable license based on course assignments). | specified in the     |            |         |
|                        |          | The number of users and subscription duration of this license below.   | e is specified       |            |         |
|                        |          | Once you activate your license in Festo LX, the subscription d   | luration will start. |            |         |
|                        |          | Licenses will not renew automatically.   |                      |            |         |
|                        |          | Access for 5 users for one year.   |                      |            |         |
|                        |          |  |                      |            |         |

## Remarks:

- Delivery according to availability
- Commissioning at site is not included. This could be ordered with 8155812.
- Technical training is not included. This could be ordered with 8155812.
- CIROS training is not included. We would recommend two days remotely. PN is 8155820.
- This offer is valid until June 2024.
- Warranty is 24 months as of day of acceptance/delivery.
- The conditions for offer, delivery, payment and software utilization printed in our current catalogue are valid. In case you do not have these, they can be obtained from your contact person. http://www.festo-didactic.com/int-en/agb